

### Description

The EPOT converts an analog voltage into digital encoder signals. The output signals may be configured to produce either an A/B quadrature output or step/direction output. The encoder signals may be further configured to provide velocity or position outputs proportional to the analog input voltage.

The single-ended output version is typically used with cables of 10 feet or less. For longer cable lengths, the differential output version is recommended. For differential versions, the internal differential line driver (26C31) can source and sink 20mA at TTL levels. The recommended receiver is industry standard 26C32. Maximum noise immunity is achieved when the differential receiver is terminated with a 150 Ω resistor in series with a .0047 μ F capacitor placed across each differential pair. The capacitor simply conserves power; otherwise power consumption would increase by approximately 20mA per pair, or 60mA for 3 pairs.

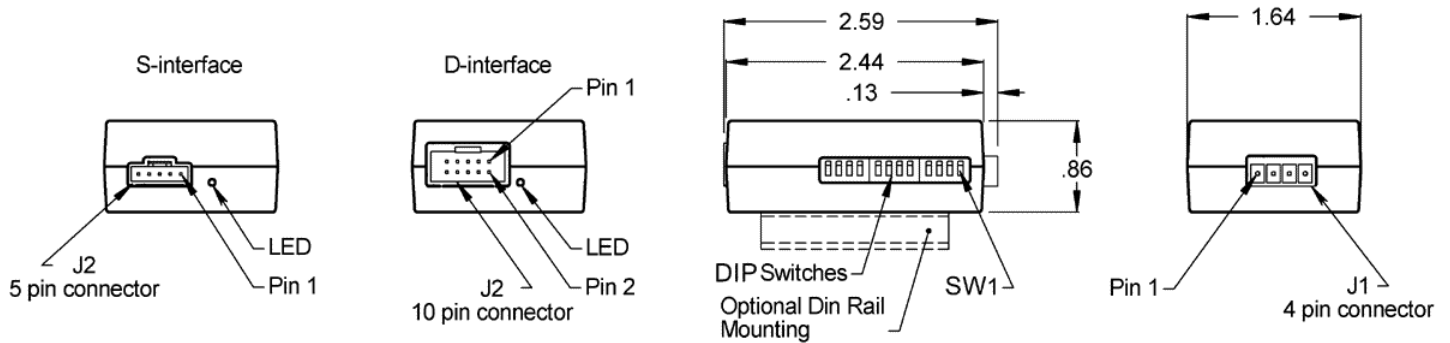
When the outputs of the EPOT are fed into a microstepping motor driver (see the MD2S data sheet), any analog voltage source such as a joystick or potentiometer can then be used to control the speed and direction of a motor.



### Features

- ▶ Analog voltage to quadrature or analog voltage to step and direction outputs
- ▶ Selectable velocity or position output mode
- ▶ Adjustable dead band
- ▶ Scalable output range
- ▶ Single-ended or differential outputs

### Mechanical Drawing



### Specifications

Parameter	Min.	Typ.	Max.	Units
Supply Voltage	4.5	5.0	5.5	V
Current Consumption		14		mA
Vout High (source 20 mA)	2.4	3.4		V

Parameter	Min.	Typ.	Max.	Units
Vout Low (sink 20 mA)		0.2	0.4	V
External Potentiometer Value	50			Ohms
Operating Temperature	0		70	C

### Timing Specifications

#### Analog Input Slew Rate:

Parameter	Min.	Typ.	Max.	Units
Position Output Mode: -2047 to 2047			73	V/sec
Position Output Mode: -1023 to 1023			200	V/sec
Position Output Mode: All Other			Unlimited	V/sec

#### Output Settling Time in Response to a Full Scale Analog Input Step Transition:

Parameter	Min.	Typ.	Max.	Units
Position Output Mode:-2047 to 2047		160 (note 1)		ms
Position Output Mode:-1023 to 1023		100 (note 2)		ms
Position Output Mode: 511 to 511		105		ms
Position Output Mode: 255 to 255		65		ms
Position Output Mode: 127 to 127		80		ms
Position Output Mode: 63 to 63		75		ms
Position Output Mode: 31 to 31		45		ms
Position Output Mode: 15 to 15		35		ms

#### Notes:

- (1) The step input was slew rate limited to a 73 V/sec rise time
- (2) The step input was slew rate limited to a 200 V/sec rise time

### DIP Switch Settings

**Note:** After changing the DIP switch settings, the EPOT must be power cycled to ensure that the device configuration is updated.

#### DIP switch 1:

Selects the maximum analog input voltage. This voltage must match the output voltage used on connector J1.

- ↑ Up (1) position for +3.6V max. analog input
- ↓ Down (0) position for +5V max. analog input.

#### DIP switch 2:

Selects either velocity output mode or position output mode.

- ↑ Up (1) position for velocity output mode.
- ↓ Down (0) position for position output mode.

### DIP switch 3:

Selects either quadrature output mode or step/direction mode.

- ↑ Up (1) position for step/direction output mode.
- ↓ Down (0) position for quadrature output mode.

### DIP switches 4, 5 and 6:

Select the output frequency (for velocity output mode) or position range (for position output mode) as shown in the tables below.

SW4	SW5	SW6	Position Output Mode	Velocity Output Mode
↓	↓	↓	-15 to 15 counts	4.1KHz CCW to 4.1KHz CW
↑	↓	↓	-31 to 31 counts	8.3KHz CCW to 8.3KHz CW
↓	↑	↓	-63 to 63 counts	16.6KHz CCW to 16.6KHz CW
↑	↑	↓	-127 to 127 counts	25.0KHz CCW to 25.0KHz CW
↓	↓	↑	-255 to 255 counts	33.3KHz CCW to 33.3KHz CW
↑	↓	↑	-511 to 511 counts	50.0KHz CCW to 50.0KHz CW
↓	↑	↑	-1023 to 1023 counts	66.6KHz CCW to 66.6KHz CW
↑	↑	↑	-2047 to 2047 counts	100.0KHz CCW to 100.0KHz CW

### DIP switches 7 and 8:

Selects the size of the dead band. The dead band is a selectable zero velocity output range. With human interface applications utilizing potentiometers or joysticks, it is difficult to return to a very precise zero velocity output location. A wider dead band makes it much easier to return a potentiometer or joystick to a zero velocity point. This adjusts the width of the zero velocity dead band in the center of a potentiometer or joystick.

SW7	SW8	Dead Band
↓	↓	0% (no dead band)
↑	↓	2%
↓	↑	4%
↑	↑	6%

### DIP switch 9:

Selects the encoder output direction. Moving this switch to the opposite state will change the direction output of the encoder signals.

- ↑ Up (1) position for normal direction on A and B.
- ↓ Down (0) position for reverse direction on A and B.

### DIP switch 10:

Selects between a standard potentiometer and joystick style potentiometer. The typical total rotation seen by a potentiometer-based joystick is about 50 degrees. This switch adds a gain of 5 to enable the limited travel of a joystick potentiometer to produce a full-scale output from the **EPOT**. If a standard potentiometer is used with the **EPOT**, the gain should be disabled. If the gain is not disabled, the EPOT will reach a maximum value over about a 50 degree rotation of a standard potentiometer.

- ↑ Up (1) position to increase input gain by a factor of 5.
- ↓ Down (0) position to disable the gain increase.

### DIP switch 11:

Selects which application is being used: potentiometer or joystick.

- ↑ Up (1) position for potentiometer applications.
- ↓ Down (0) position for joystick applications.

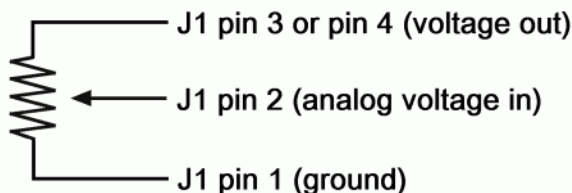
DIP switch 11 is only active when the **EPOT** is set up in velocity output mode. This switch determines how the **EPOT** will detect the zero velocity position of the potentiometer or joystick attached to its analog input. The Up (1) position will calculate a midpoint location which provides zero velocity output when power is applied. The Down (0) position will assume the potentiometer or joystick is located in its midpoint or zero velocity position when power is applied

## Pin-outs

### J1 Connector Pin-out:

Pin	Description
1	Ground
2	Analog voltage input
3	+5VDC output
4	+3.6VDC regulated output

### Typical connection:



### J2 Pin-out (Single-ended version):

Pin	Description
1	Ground
2	NC
3	A output / Step output
4	+5VDC input power
5	B output / Direction output

**J2 Pin-out (Differential output version):**

Pin	Description
1	Ground
2	Ground
3	NC
4	NC
5	A- output / Step- output
6	A+ output / Step+ output
7	+5VDC input power
8	+5VDC input power
9	B- output / Dir- output
10	B+ output / Dir+ output

### Ordering Information

EPOT -  -

**Interface**

S = *Single-ended*

D = *Differential*

**Mounting**

D = *Default*

R = *DIN rail (35mm wide)*

**Notes**

- Cables and connectors are not included and must be ordered separately.
- US Digital warrants its products against defects in materials and workmanship for two years. See complete warranty for details.